

3/28/2023

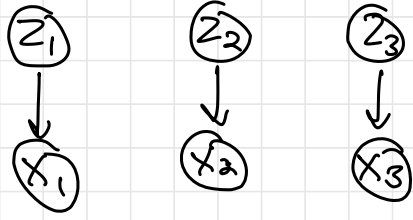
Hidden Markov Model (HMM)

GMM

Dataset = $\{x^{(1)}, \dots, x^{(n)}\}$

Each $x^{(i)}$ comes from a latent cluster Z_i :

Each Z_i drawn independently



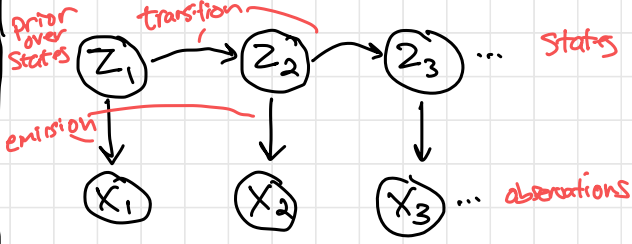
HMM

Data sequence: x_1, \dots, x_T

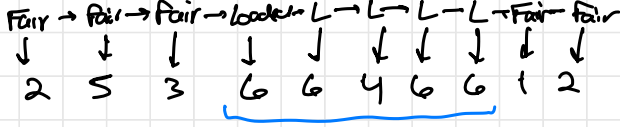
$T =$ total timesteps

Each observation x_t has latent state Z_t

Each Z_t depends on previous state Z_{t-1}



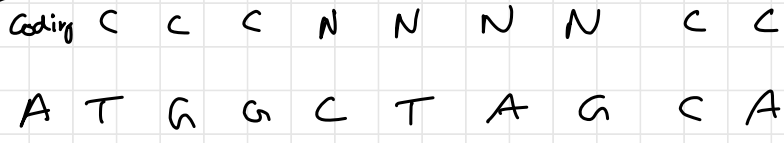
Casino dice game



State: Fair dice or loaded dice

Observations: dice rolls

Genomics



State: coding vs non-coding

Observations: DNA base pairs

Speech Recognition



States: words/syllables

Observation: Audio

HMM (formal): Probabilistic Model of a
 Sequence of observations x_1, \dots, x_T

① Sample z_1 from prior distribution $\pi_{1:k}$ (k possible states)
 $P(z_1 = c) = \pi_c$

② For each $t=2, \dots, T$
 Sample z_t from $p(z_t | z_{t-1})$

Markov Assumption:

z_t only depends on z_{t-1}
 not on other history

Also assume same transition
 probabilities (ie same A)
 at each time

Represent as $k \times k$ matrix A
 where $A_{ij} = P(z_t = j | z_{t-1} = i)$

$i =$

	$j=1$	2	3	4
1				
2	.1	.3	.4	.2
3				
4				

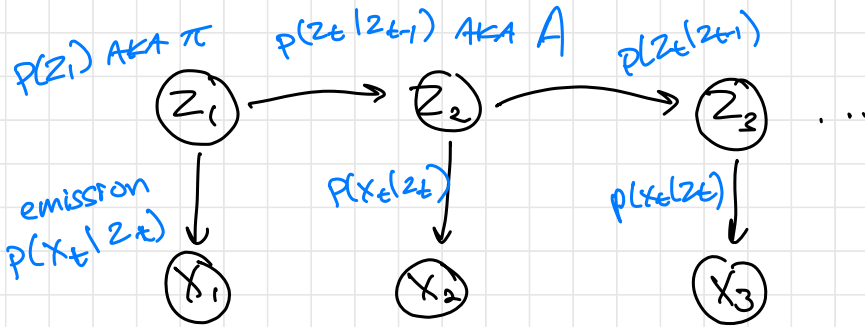
③ For each $t=1, \dots, T$
 Sample x_t from $p(x_t | z_t)$

Genomics: $p(x_t | z_t)$ is
 distribution over $\{A, C, G, T\}$
 for each value of z_t

Assume that x_t only depends
 on z_t (not past states
 or observations)

Speech: $p(x_t | z_t)$ is
 Gaussian in audio feature space

Assume emission distribution
 is same for all times t



HW3: Out tonight

Inference in HMMs z_1, \dots, z_T

x_1, \dots, x_T

Inferring values of latent variables given observations
Assuming we know:

- ① π i.e. $P(z_1)$
- ② A i.e. $P(z_t | z_{t-1})$
- ③ $P(x_t | z_t)$

} Next class: learn these

Given observations x_1, \dots, x_T we could try to infer:

Ⓐ Most likely sequence of $z_1 \dots z_T$ e.g. given audio, find most likely sequence of words

$$\operatorname{argmax}_{z_{1:T}} P(z_{1:T} | x_{1:T})$$

Ⓑ At a particular time t , what is distribution of z_t ?
e.g. in Castro, how likely was the player cheating at time 9

$$P(z_t | x_{1:T})$$

A: Viterbi Algorithm

$$\operatorname{argmax}_{z_{1:T}} P(z_{1:T} | x_{1:T}) = \operatorname{argmax}_{z_{1:T}} P(z_{1:T}, x_{1:T})$$

↖ Differ by factor of $P(x_{1:T})$ ↗

Strategy: Dynamic Programming

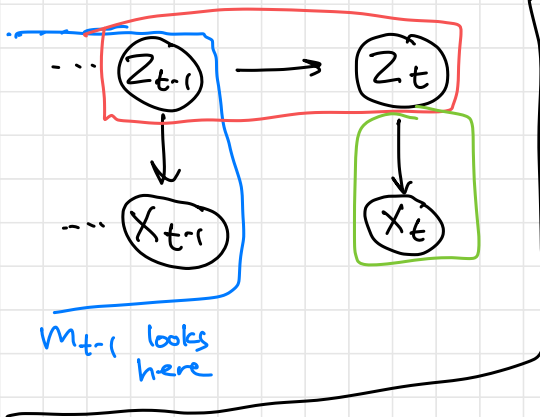
$$M_{t,j} = \max_{\substack{z_{1:t} \\ \text{where} \\ z_t = j}} P(z_{1:t}, x_{1:t})$$

Probability of best sequence of states upto time t where we end at state j

$$m_{t,j} = \max_{i=1, \dots, k} \underbrace{P(z_t=j | z_{t-1}=i)} m_{t-1,i} \underbrace{P(x_t | z_t=j)}$$

$$b_{t,j} = \operatorname{argmax}_{i=1, \dots, k} P(z_t=j | z_{t-1}=i) m_{t-1,i} P(x_t | z_t=j)$$

"backpointers"



States

	1	2	3
t=1			
2			
3			
T			

↑ longest M_{Tj}

base case

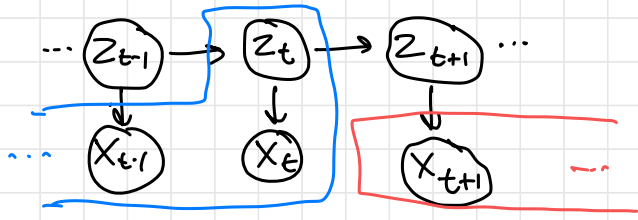
b	1	2	3
1	-	-	-
2	2	3	2
3	3	2	1
4	2	2	3

extract best $Z_{1:4} = [3, 2, 2, 1]$

Base case $t=1$: $M_{ij} = P(z_1=j) P(x_1 | z_1=j) \forall j=1, \dots, k$
 For $t=2, \dots, T$
 compute M_{tj} given $M_{t-1,j}$ $\forall j=1, \dots, k$
 and b_{tj}

At the end:
 Best ending state $Z_T = \underset{j=1 \dots k}{\text{argmax}} M_{Tj}$
 extract best path by following b_{tj} 's

B Inference on z_t



- To infer $p(z_t | x_{1:T})$ we need to reason about:
- ① z_t 's effect on x_t
 - ② How past influences z_t
 - ③ How z_t affect future

$$p(z_t | x_{1:T}) = \frac{p(z_t, x_{1:T})}{p(x_{1:T})} = \frac{p(x_{1:t}, z_t) p(x_{t+1:T} | z_t)}{p(x_{1:T})}$$

Normalizing constant:
 Compute numerator for all choices of z_t then normalize

Compute recursively